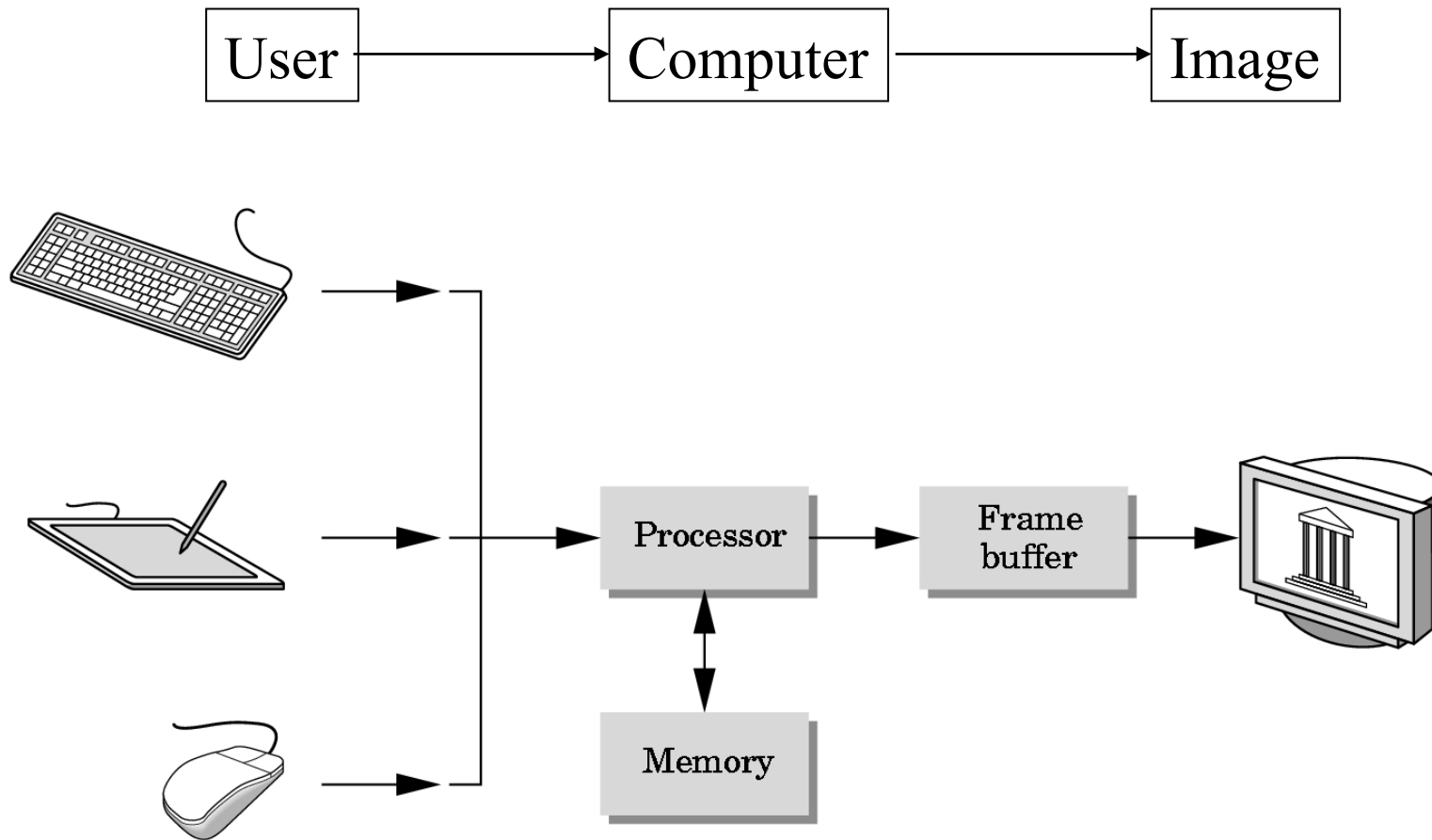


Introduction to Computer Vision & Graphics

Reading: Angel ch.1 or Hill Ch1.

What is Computer Graphics?

‘Synthesis of images’



What are Computer Vision & Graphics?

Graphics: ‘Synthesis of images’



Vision: ‘Analysis of images’



Vision is the inverse problem of Graphics

Graphics goes from a model of the world to images

Vision from images of the world to models

Computer Graphics Applications

2D Display

Text

User Interfaces (GUI)

- web
- draw/paint programs

Data Visualisation

- bar charts/graphs etc.

3D Modelling Shape

Architecture

Engineering Design CAD

3D Modelling Shape + Appearance

VR Simulation

Video Games

Film Animation

Computer Vision Applications

2D image analysis:

- text recognition

- industrial inspection (PCB, manufacture)

2D scene analysis from video:

- number plate recognition

- TV sports annotation (Piero, iview)

- surveillance, behavior analysis

- object recognition

3D scene analysis from video:

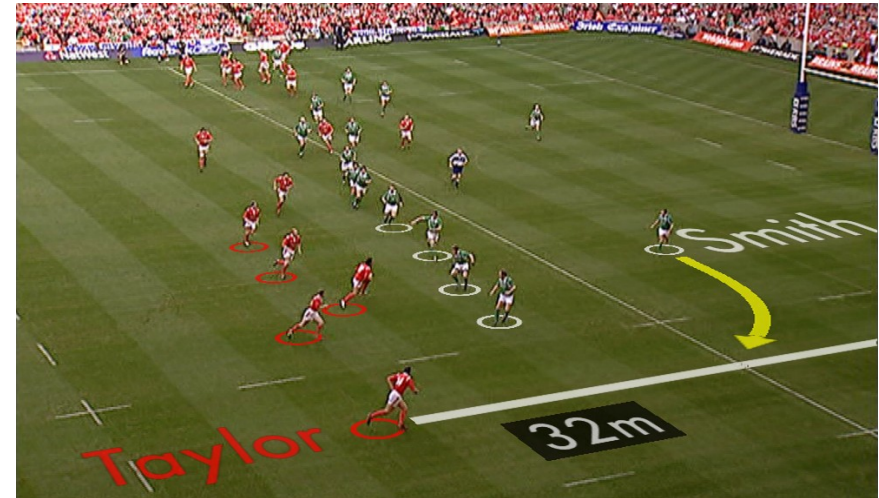
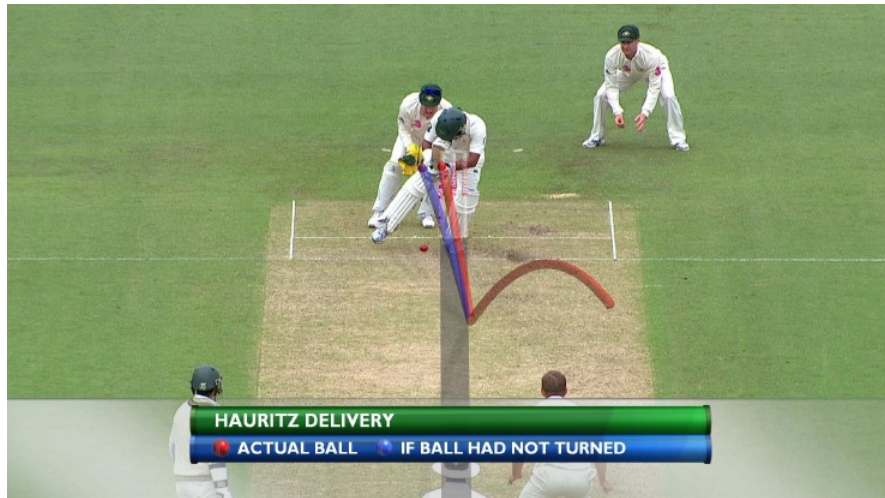
- human motion capture (markers)

- camera tracking – film production

- 3D scene reconstruction (objects, building, games)

Analysis, modelling and understanding of real-scenes from images

Computer Vision Applications in Sports



Brief History of Computer Graphics

Whirlwind Computer - MIT 1950

- CRT Display
- SAGE Air Defense mid 50' s
 - Whirlwind II used light pen for interaction

Sketchpad - Sutherland 1963

- First interactive graphical system
- Interaction for 'select', 'point', 'draw'
- Data structures for repeating component shapes

Further Development driven by:

Design 60/70' s - interactive drawing in 2D/3D

Games/Simulation/Visulisation 70/80' s - 3D display

Film Animation 80/90' s - Realistic special effects

- Feature length movies

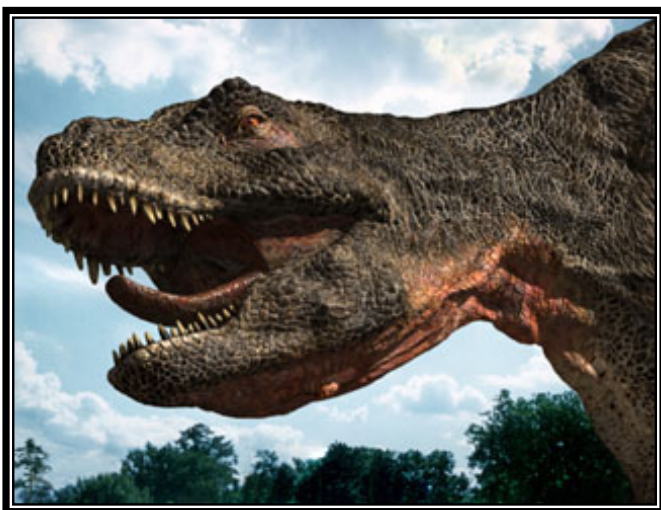
Current CGI State-of-the-art

Low-cost PC/console graphics

- web-based 3D (web3D)
- games
- Real-time user interaction
- real-time data/process visualisation

‘Realistic’ computer generated characters and effects

- complex physical modelling (water/fire...)
ie Antz, Bugs Life
- frame-by-frame animation of characters
ie Toy Story, Shrek(Pixar/Disney)
- photo-realistic faces
ie Benjamin Button (2009), Beowulf (2007)
- computer generated extras ie Titanic
- integration of synthetic characters & real actors
ie Star Wars - Episode I



Disney: Gemini Man



Sony: Beowulf

Motion capture

- performance capture with 200 Vicon cameras
- ~200 facial markers
- CG performance of real actors



Sony Image works – Beowulf (2007)

Current Research in Graphics

‘Photo-realistic’ image synthesis

- synthesis of images which are indistinguishable from the real thing (matrix) (fiat-lux)
- real-time video rate generation

Realistic Modelling of people

- shape, apperance, movement, behaviour
- synthetic actors ‘synthespians’ & virtual presenters
- digital doubles

Real-time integration of live and computer generated content

This course will introduce current techniques for computer generated image production (nuts & bolts)



'What is Bullett Time'
(c) 1999 Home Box Office, Time Warner Entertainment

Image Formation

Real camera:

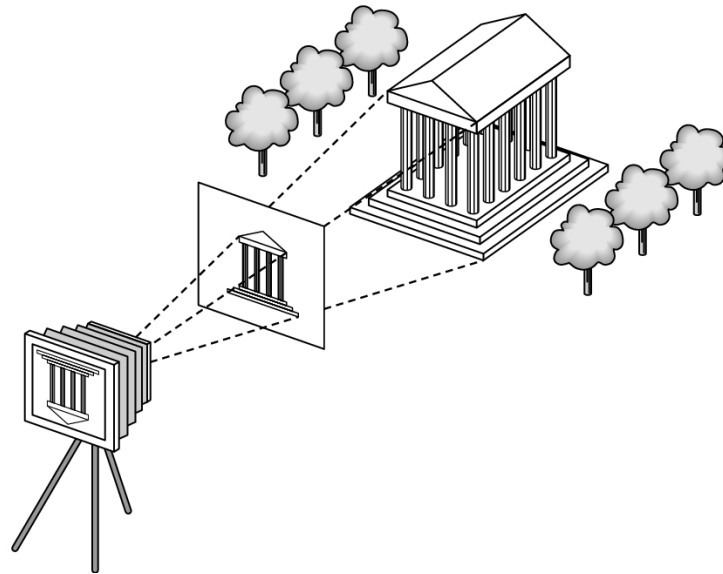
Real scene



Physics of image formation



Image



Computer graphics simulates the physics of real image formation

Synthetic camera:

Graphical model



**Synthetic
physics of image formation**



Synthetic Image

Image Formation

How are real images formed?

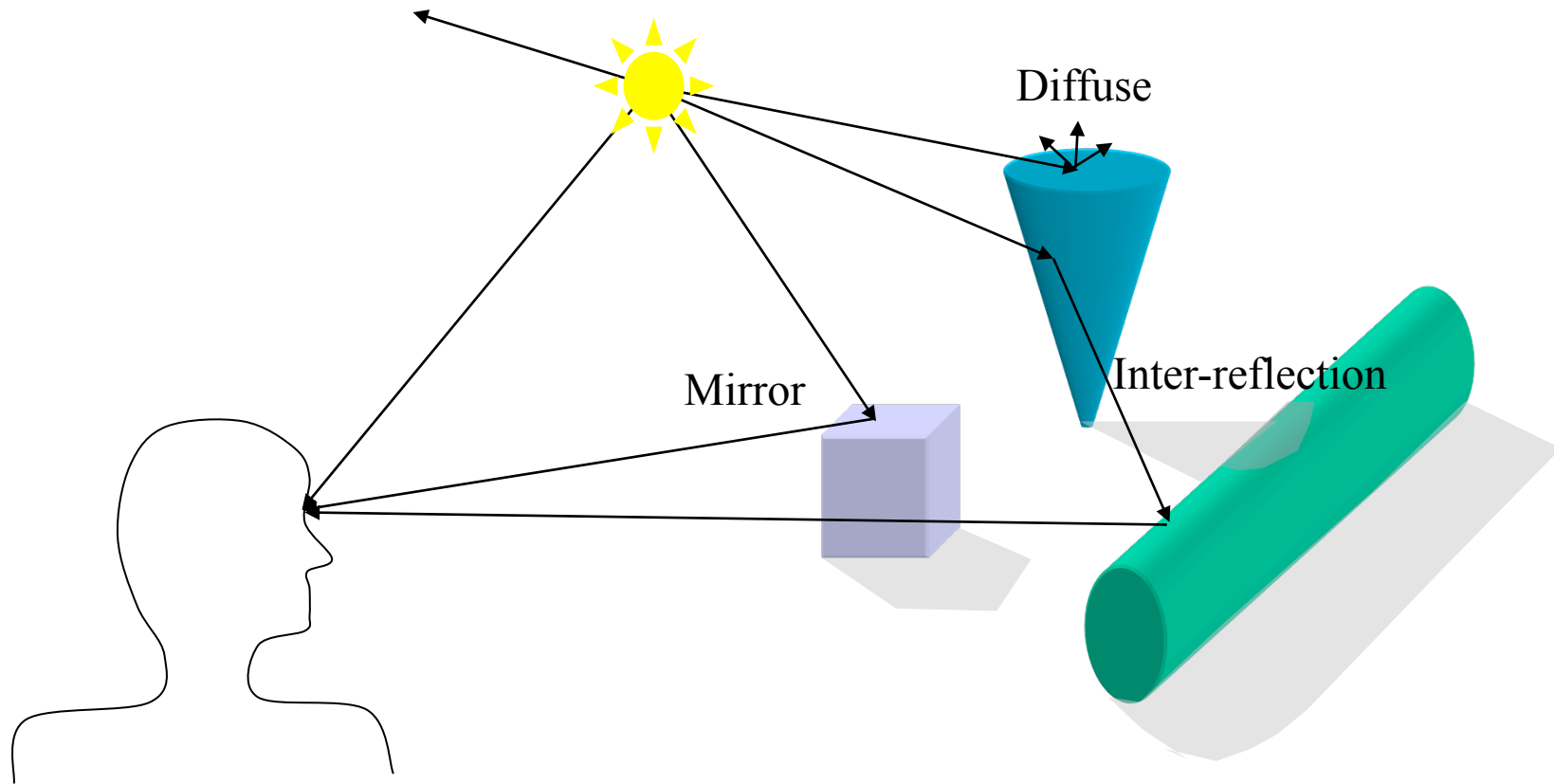
Ray-tracing model of image formation

- (1) Lights emit rays of light
- (2) Some rays hit objects & illuminate the surface
- (3) Some rays are reflected back off objects to the viewer

If we trace the path of all rays in the scene we can model the physical image formation process.

Ray-tracing can be used to simulate complex physical effects and generate highly realistic images

Ray-Tracing



Ray-tracing traces the path of each light-ray in the scene

- highly realistic (physics-based)
- very high computational cost (not real-time)

What Affects Image Formation?

- Illumination:**
- location
 - point/area & directional/ambient
 - colour
- Objects:**
- surface shape/smoothness
 - surface material colour/texture
 - surface reflectance (mirror/diffuse)
 - surface opacity/transparency
- Viewer:**
- viewpoint/direction
 - focal-length/field-of-view
 - sensor type (eye/CCD)

A simplified model for image formation

Ray-tracing produces highly realistic images but is **SLOW**

How can we produce ‘realistic’ images at video rate?

Observation 1: To the viewer a surface illuminated by a light source appears exactly the same as a surface emitting light.

Observation 2: Multiple light rays hitting a surface are additive
- there is no such thing as negative light.

Therefore, we can model a scene as a set of objects which emit light:

- fast
- realistic (no shadows/inter-reflections)

Synthetic Image Generation

Three-dimensional computer graphics



Model is a three-dimensional (3D) representation of the scene

Renderer is a synthetic-camera model which generates images from the 3D object model

Image is a two-dimensional digital image of the scene from a particular viewpoint

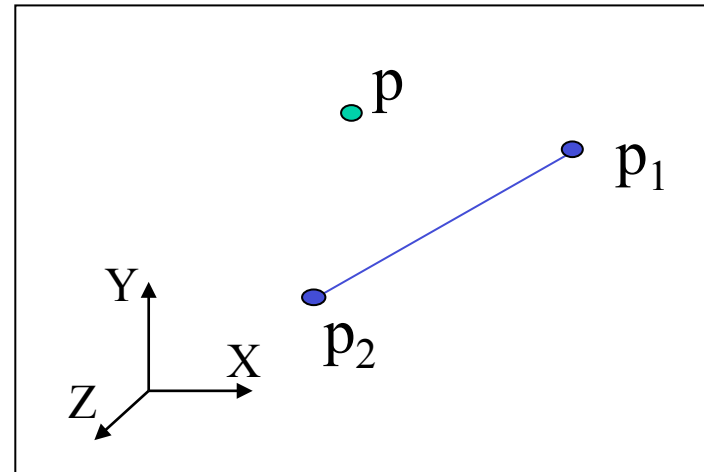
For image generation we must consider each component

Three-Dimensional Modelling

An arbitrary 3D scene can be built from simple primitives: point, lines and polygons.

Point: $p = (x, y, z)$

Line: $l = (p_1, p_2)$

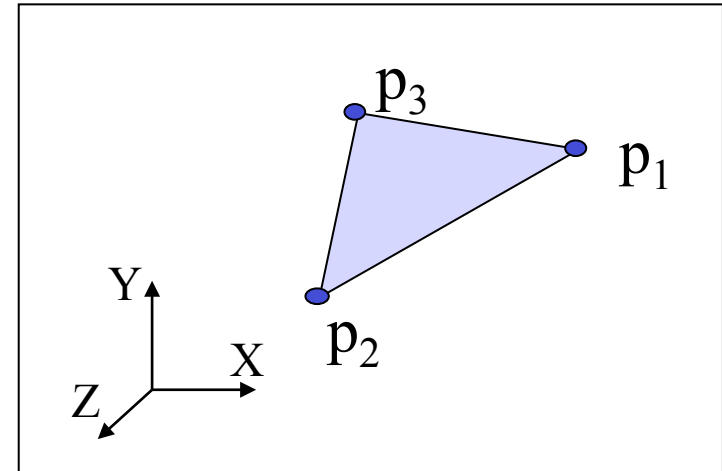


Three-Dimensional Modelling II

Polygons: Triangle $t = (p_1, p_2, p_3)$

Quadrilateral $q = (p_1, p_2, p_3, p_4)$

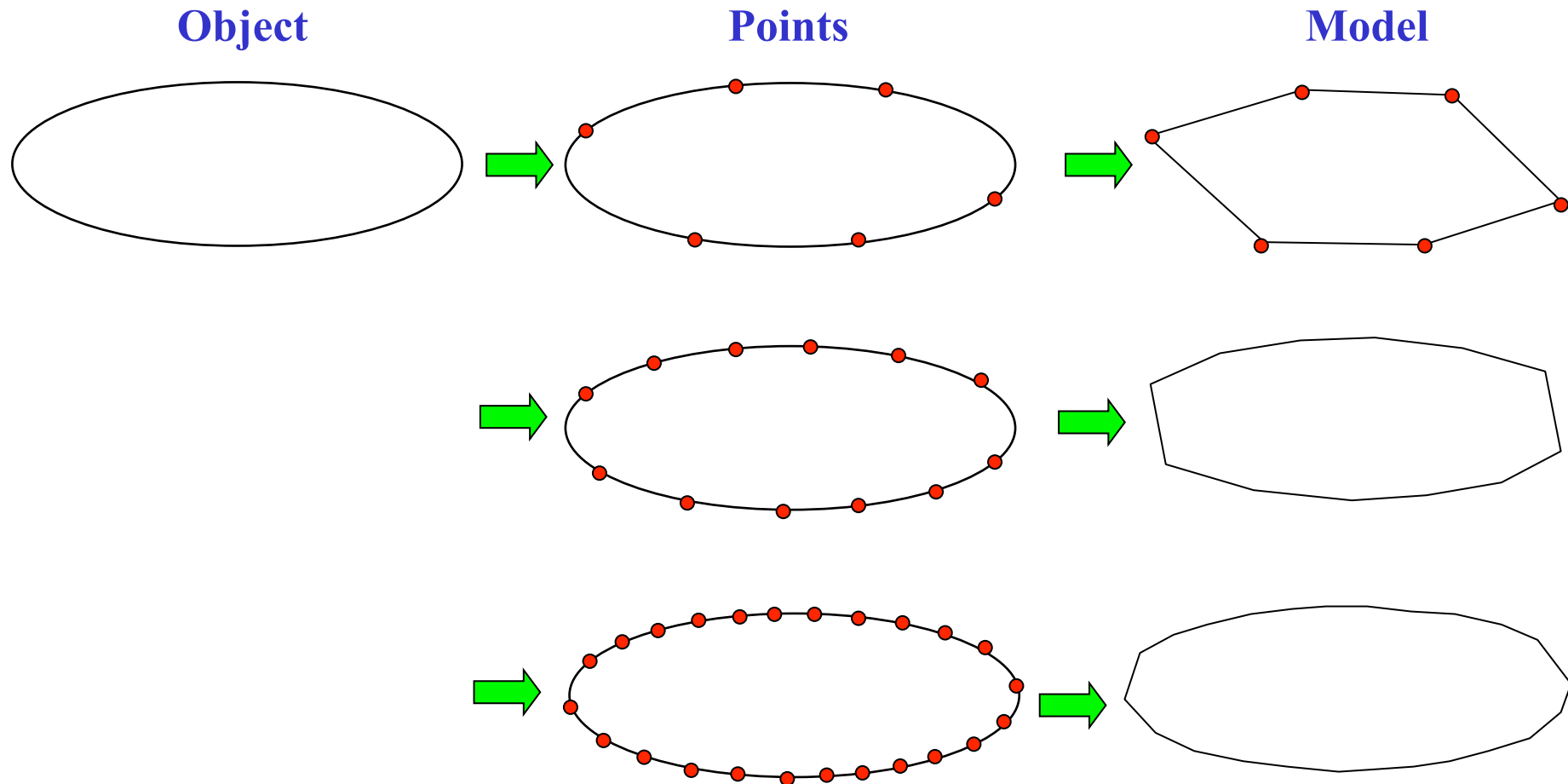
N-gon $r = (p_1, \dots, p_N)$



- N-gon can be exactly represented by triangulation
- Triangles are the most common primitives in graphics
- Complex surfaces are approximated by thousands of polygons

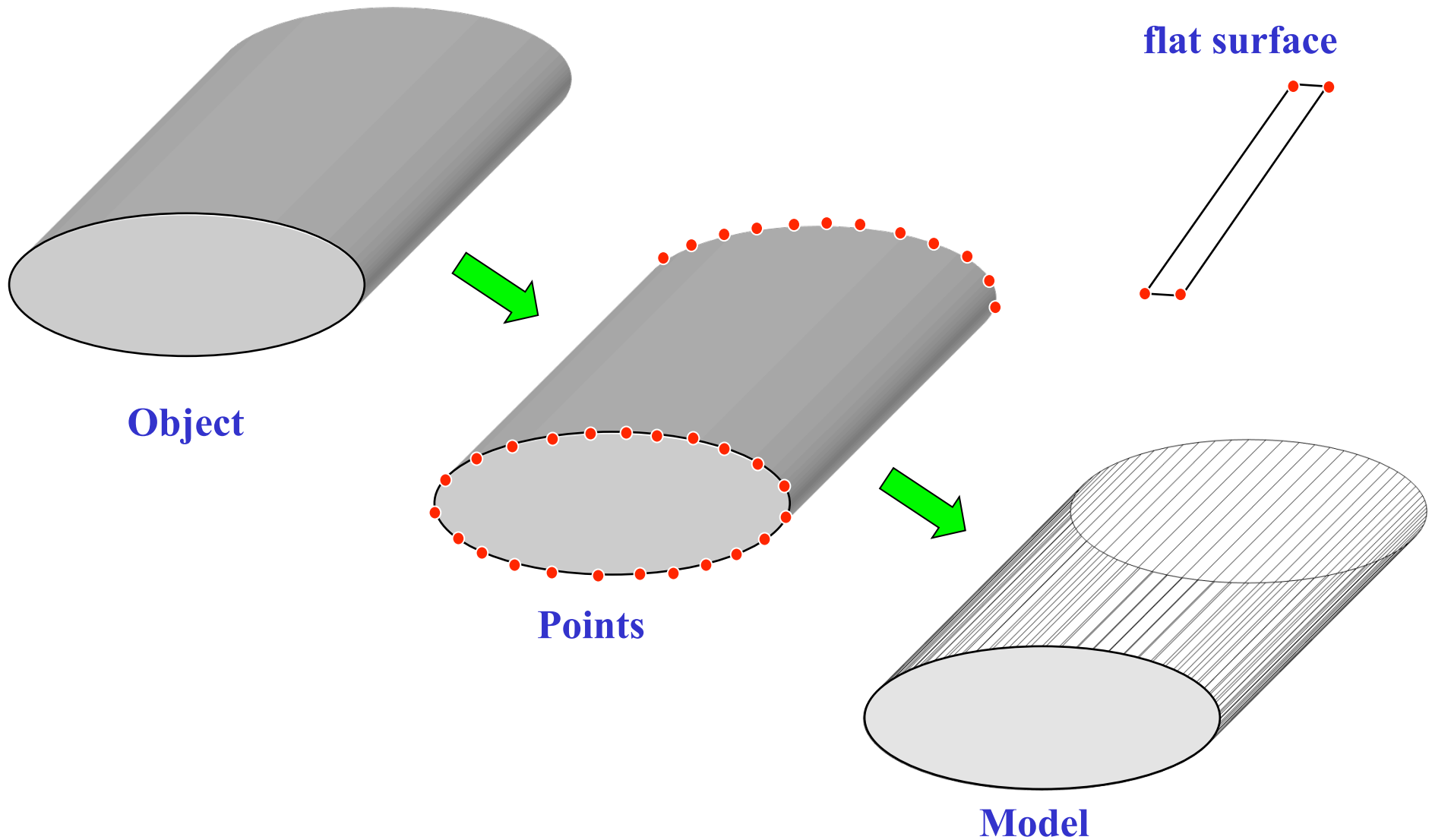
Modelling Object Shape in a Flat World

In a flat world a curved object can be modelled by lines



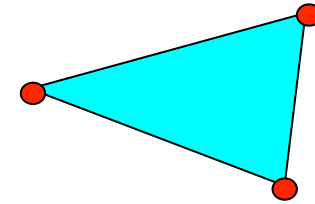
Modelling Object Shape in the Real World

Surface shape can be modelled by small flat surfaces

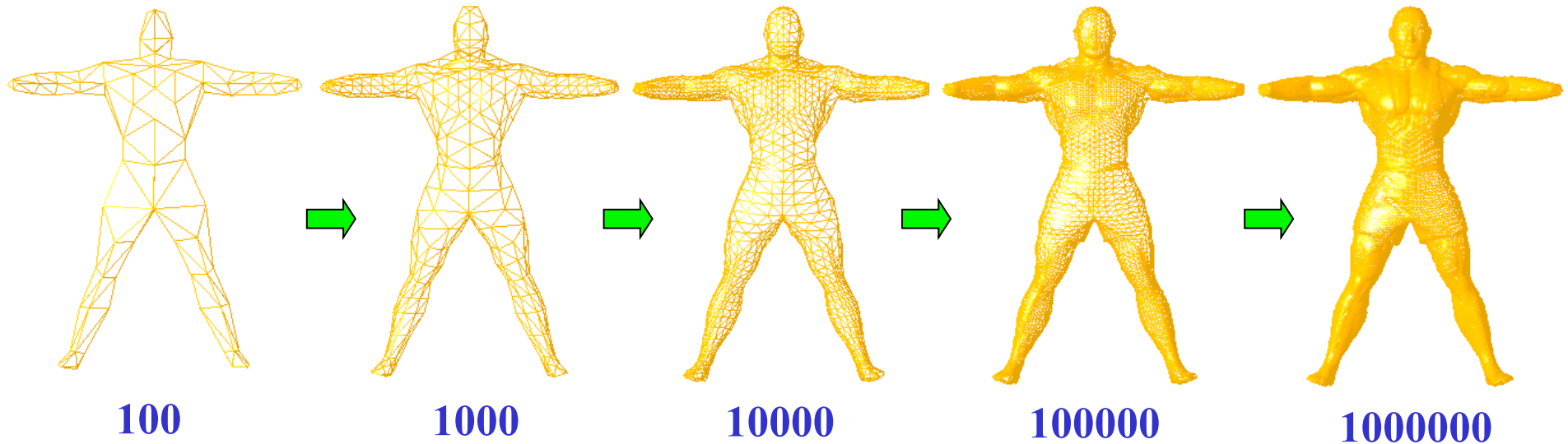


Modelling Surface Shape

A flat surface is defined by 3 points: 'triangle'

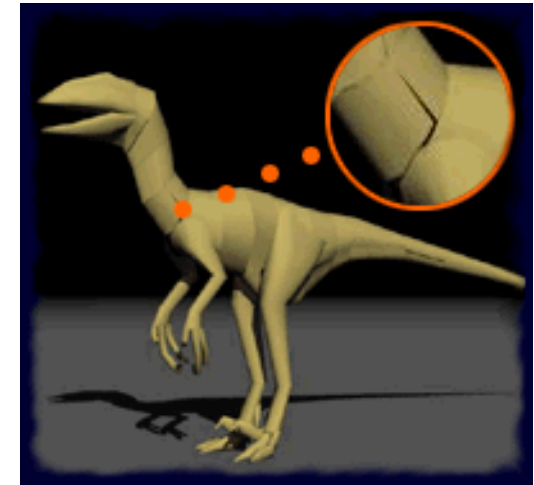


Triangles are joined into 'meshes' to model any object surface shape



Example: Animated Models for 'Walking with Dinosaurs'

(1) Animation Skeleton + Patch Model



(2) Combine detailed surface mesh model and animation model



(3) Model surface appearance (colour/reflectance)

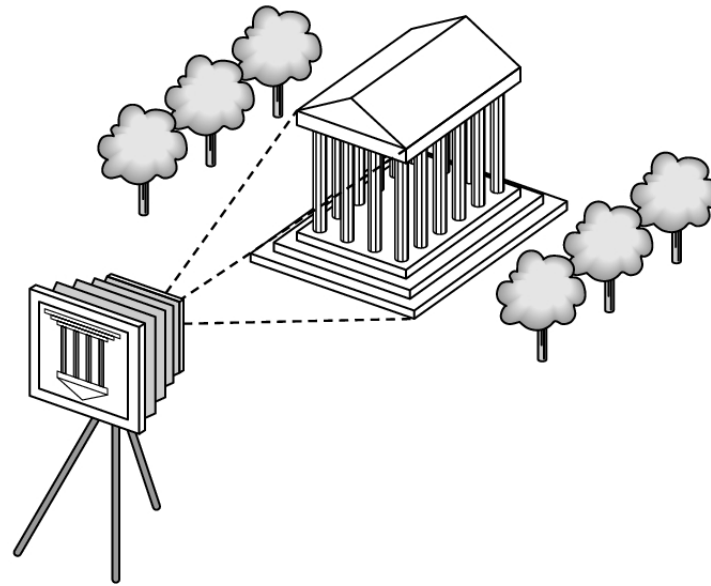


(4) Illuminate the scene



Synthetic Camera Model

Model the **projection** of the 3D scene onto the **image plane**

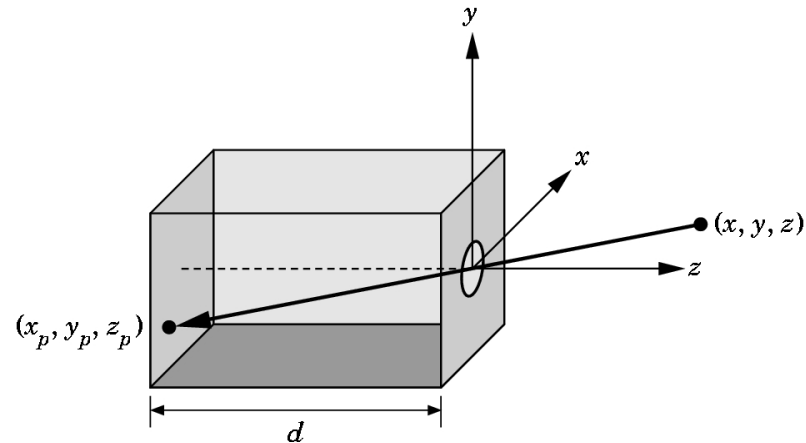


Note: Specification of the 3D scene is independent of the specification of the viewer.

Pin-hole Camera Model

Pin-hole camera is a box with a small hole on one side.

- A single ray of light passes through the hole and is projected onto the image plane on the opposite side.



If the Z-axis is aligned with the camera **optical axis** then a point $p=(x,y,z)$ is projected to a point $p_p=(x_p,y_p,z_p)$ on the image plane:

$$x_p = - (xd)/z \quad y_p = -(yd)/z \quad z_p = -d$$

where d is the distance of the image plane from the **centre of projection**

Note: z_p is constant for all p_p ie the depth of the image plane $p_p=(x_p,y_p)$

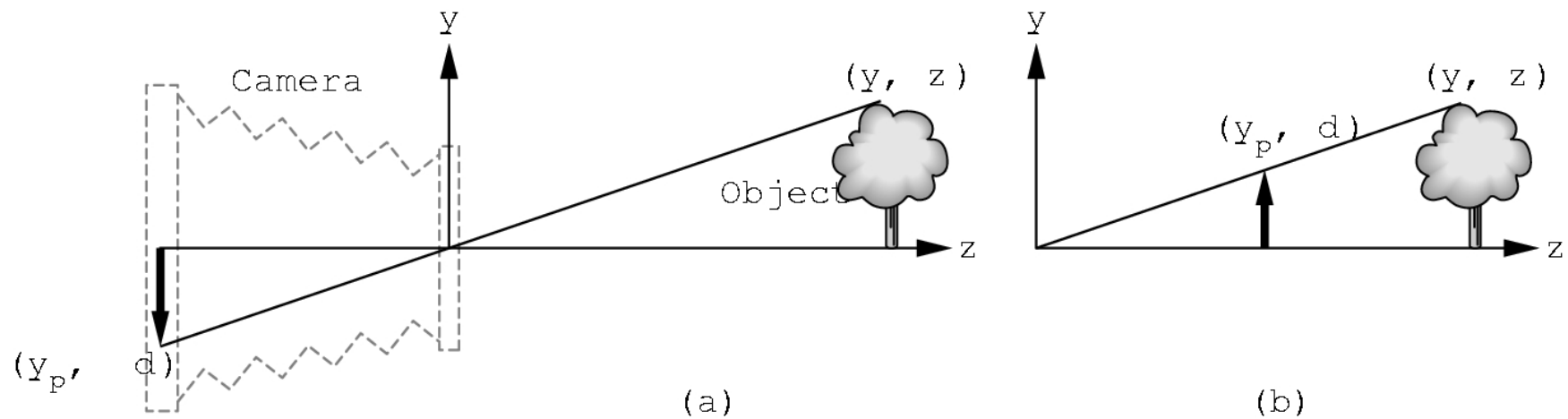
Pin-hole Camera II

An equivalent image is formed if the image plane is placed in front of the camera at distance d :

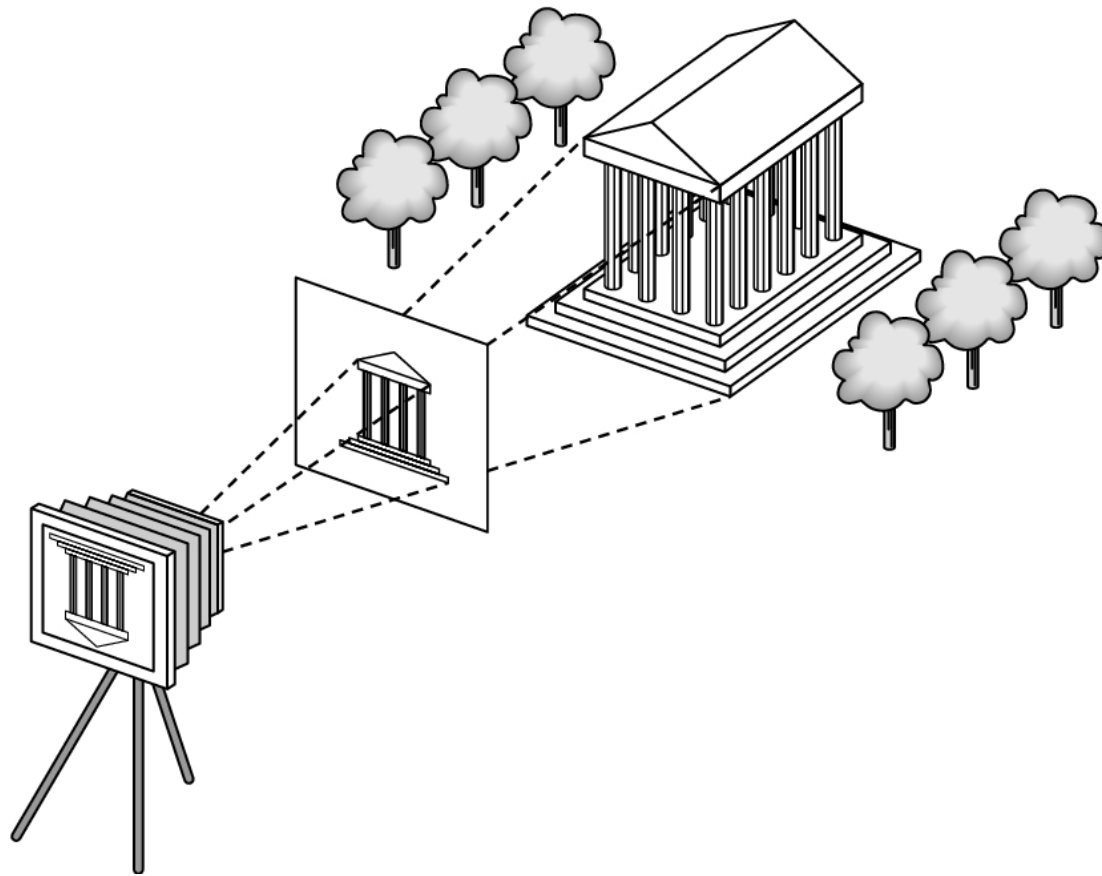
$$x_p = (xd)/z$$

$$y_p = (yd)/z$$

$$z_p = d$$



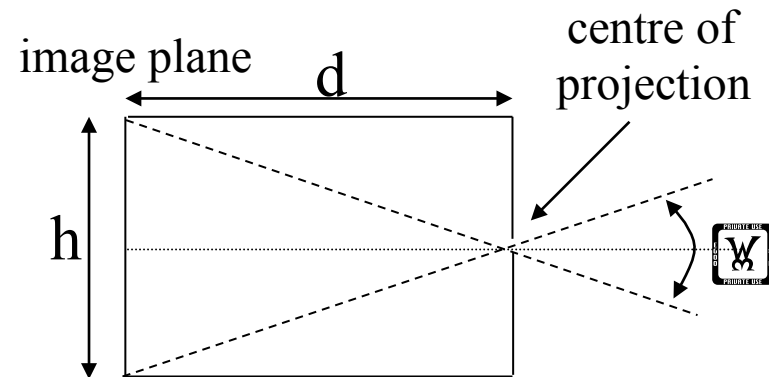
Synthetic camera model: Each point in the 3D model is projected onto the image plane using the pin-hole camera model



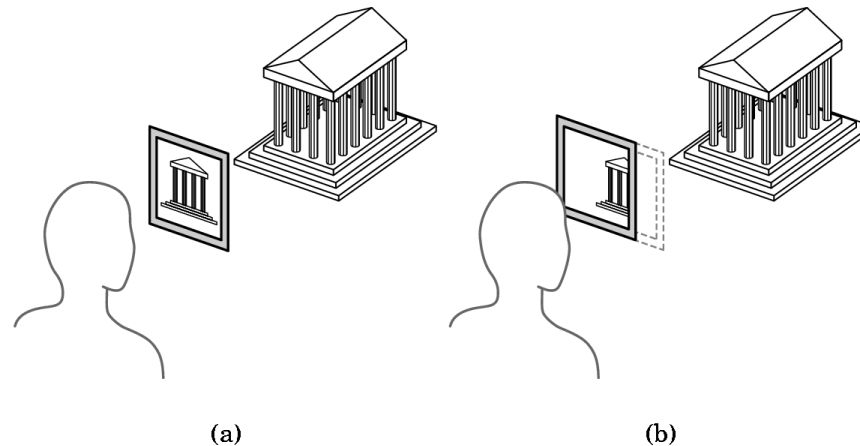
Synthetic Camera - Field-of-view

The field-of-view (fov) for a pin-hole camera is determined by the height of the image plane h and the distance d from the centre of projection:

$$\text{fov} = 2 \tan^{-1} h/(2d)$$



Clipping is performed to eliminate parts of the scene outside the fov



Modelling Surface Appearance

4 main factors:

Shape

Colour

Shininess

Lighting

Model appearance by:

(1) Colouring triangles

(2) Simulating physics of surface reflection

Synthesize object appearance for each flat surface separately

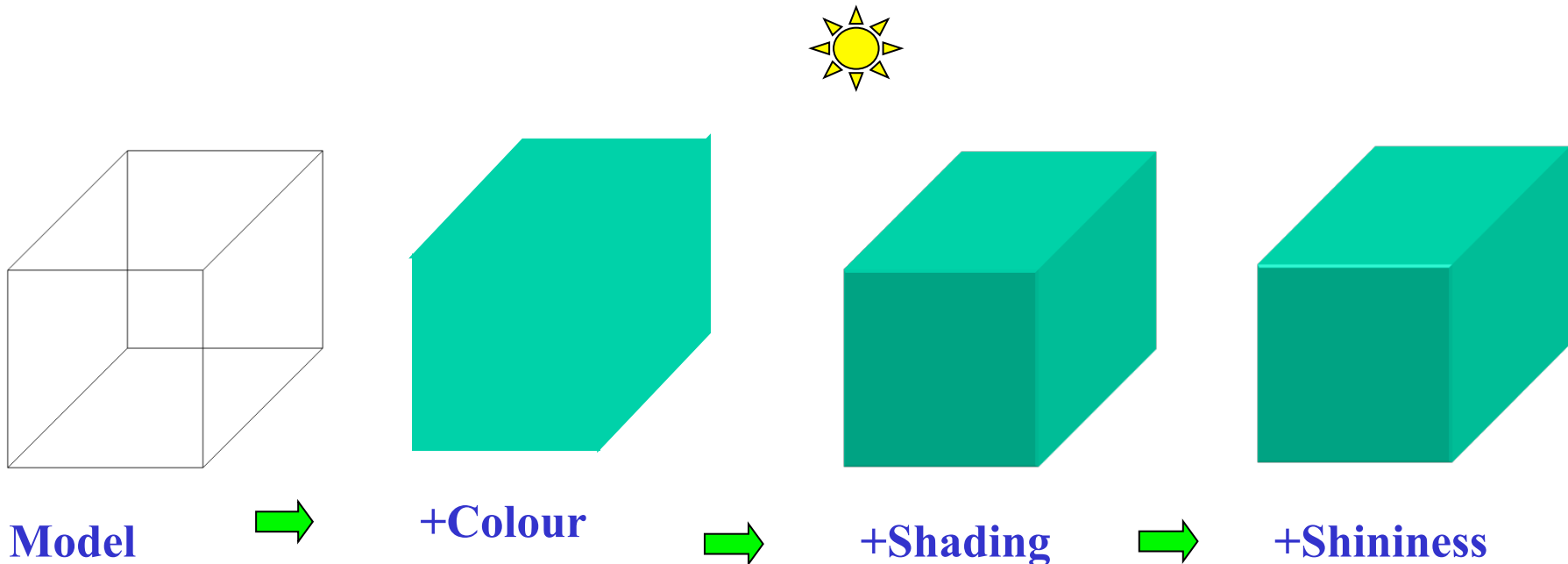
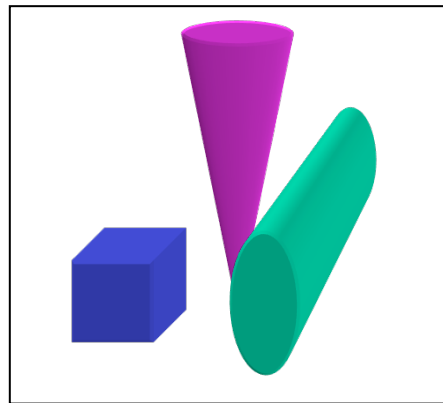


Image Sampling - Rasterisation

Image projection forms a continuous scene projection
in the camera image plane

Rasterisation samples the projection onto a discrete grid of ‘**pixels**’
in the image plane to generate a digital image
Each pixel stores the colour of the surface
which projects to that pixel.

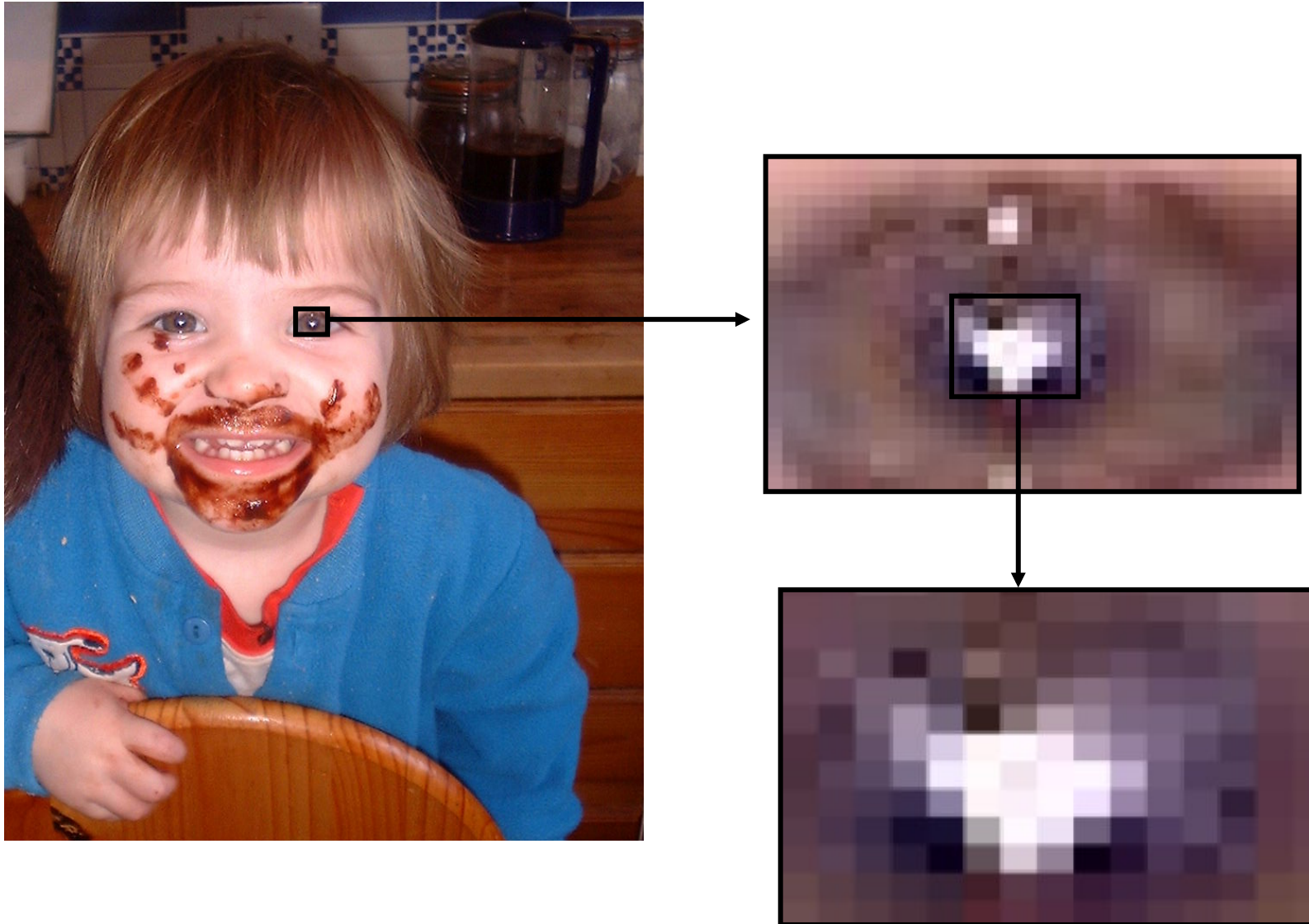


20x20grid

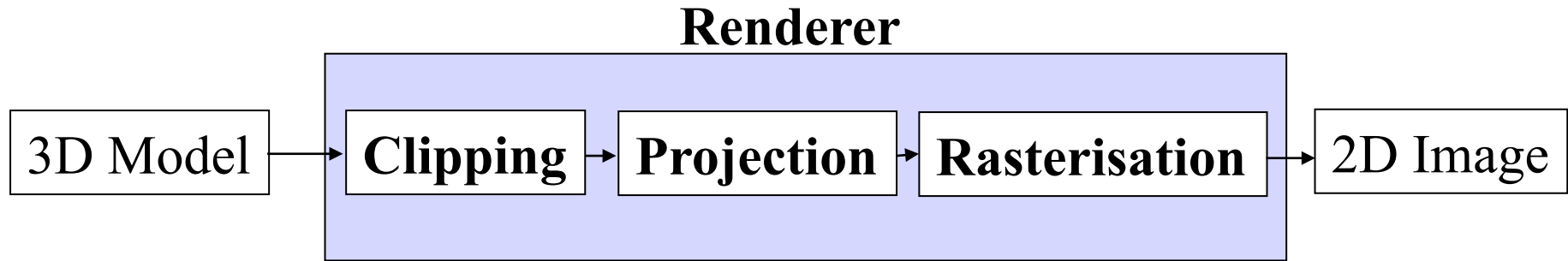


40x40grid

Image Sampling - Digital Camera



Synthetic Image Generation - Graphics Pipeline



Renderer - Synthetic camera model

Clipping - Eliminate parts of the scene outside the field of view

Projection - Project the 3D Scene onto the image plane

Rasterisation - Sample the projection on a discrete image grid